

# Biostatistics 615/815 Lecture 4: Classes and Libraries, and Divide and Conquer Algorithms

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## Recap - Call by value vs. Call by reference

### callByValRef.cpp

```
#include <iostream>
int foo(int a) { // a is an independent copy of x when foo(x) is called
    a = a + 1;
    return a;
}
int bar(int& a) { // a is an alias of y when bar(y) is called
    a = a + 1;
    return a;
}
int main(int argc, char** argv) {
    int x = 1, y = 1;
    std::cout << foo(x) << std::endl; // prints ??
    std::cout << x << std::endl; // prints ??
    std::cout << bar(y) << std::endl; // prints ??
    std::cout << y << std::endl; // prints ??
    return 0;
}
```

## Recap - Precision for very large values

### intFac() - only calculates up to 12!

```
int intFac(int n) { // calculates factorial
    int ret;
    for(ret=1; n > 0; --n) { ret *= n; }
    return ret;
}
```

### dblFac() - calculates up to 170!

```
double dblFac(int n) { // main() function remains the same
    double ret; // use double instead of int
    for(ret=1.; n > 0; --n) { ret *= n; }
    return ret;
}
```

## Recap - Precision for very large values

### logFac() - Allows much larger range

```
double logFac(int n) {
    double ret;
    for(ret=0.; n > 0; --n) { ret += log((double)n); }
    return ret;
}
```

## Improving Time Complexity

logFac() :  $\Theta(n)$  of log() calls

```
double logFac(int n) {
    double ret;
    for(ret=0.; n > 0; --n) { ret += log((double)n); }
    return ret;
}
```

Fisher's Exact Test requires :  $\Theta(n^2)$  of log() calls

```
for(int x=0; x <= n; ++x) { // among all possible x
    if ( a+b-x >= 0 && a+c-x >= 0 && d-a+x >=0 ) { // consider valid x
        double l = logHypergeometricProb(x,a+b-x,a+c-x,d-a+x);
        if ( 1 <= logpCutoff ) pFraction += exp(1 - logpCutoff);
    }
}
```

## Precomputing factorials reduces log() calls to $\Theta(n)$

function initLogFacs()

```
void initLogFacs(double* logFacs, int n) {
    logFacs[0] = 0;
    for(int i=1; i < n+1; ++i) {
        logFacs[i] = logFacs[i-1] + log((double)i); // only n times of log() calls
    }
}
```

function logHyperGeometricProb()

```
double logHypergeometricProb(double* logFacs, int a, int b, int c, int d) {
    return logFacs[a+b] + logFacs[c+d] + logFacs[a+c] + logFacs[b+d]
        - logFacs[a] - logFacs[b] - logFacs[c] - logFacs[d] - logFacs[a+b+c+d];
}
```

## C++ class example : Point

```
#include <iostream>
#include <cmath>
class Point {
public:
    double x, y; // member variables
    Point(double px, double py) { x = px; y = py; } // constructor
    double distanceFromOrigin() { return sqrt( x*x + y*y ); }
    double distance(Point& p) { // distance to another point
        return sqrt( (x-p.x)*(x-p.x) + (y-p.y)*(y-p.y) );
    }
    void print() { // print the content of the point
        std::cout << "(" << x << ", " << y << ")" << std::endl;
    }
};
int main(int argc, char** argv) {
    Point p1(3,4), p2(15,9); // constructor is called
    p1.print(); // prints (3,4)
    std::cout << p1.distance(p2) << std::endl; // prints 13
    return 0;
}
```

## C++ class example - Rectangle

```
class Rectangle { // Rectangle
public:
    Point p1, p2; // rectangle defined by two points
    // Constructor 1 : initialize by calling constructors of member variables
    Rectangle(double x1, double y1, double x2, double y2) : p1(x1,y1), p2(x2,y2) {}
    // Constructor 2 : from two existing points
    Rectangle(Point& a, Point& b) : p1(a), p2(b) {}
    double area() { // area covered by a rectangle
        return (p1.x-p2.x)*(p1.y-p2.y);
    }
};
```

## Initializing objects with different constructors

```
int main(int argc, char** argv) {
    Point p1(3,4), p2(15,9); // initialize points
    Rectangle r1(3,4,15,9); // constructor 1 is called
    Rectangle r2(p1,p2); // constructor 2 is called
    std::cout << r1.area() << std::endl; // prints 60
    std::cout << r2.area() << std::endl; // prints 60
    r1.p2.print(); // prints (15,9)
    return 0;
}
```

## Pointers to an object : objectPointers.cpp

```
#include <iostream>
#include <cmath>
class Point { ... }; // same as defined before
int main(int argc, char** argv) {
    // allocation to "stack" : p1 is alive within the function
    Point p1(3,4);
    // allocation to "heap" : *pp2 is alive until delete is called
    Point* pp2 = new Point(5,12);
    Point* pp3 = &p1; // pp3 is simply the address of p1 object
    p1.print(); // Member function access - prints (3,4)
    pp2->print(); // Member function access via pointer - prints (5,12)
    pp3->print(); // Member function access via pointer - prints (3,4)
    std::cout << "p1.x = " << p1.x << std::endl; // prints 3
    std::cout << "pp2->x = " << pp2->x << std::endl; // prints 5
    std::cout << "(*pp2).x = " << (*pp2).x << std::endl; // same to pp2->x
    delete pp2; // allocated memory must be deleted
    return 0;
}
```

## A quick UNIX tip : dos2unix

- If you create your source file in Windows and upload the source using WinSCP, sometimes you may encounter warnings from compiler, such as 'No newline at end of file'
- This happens due to slight difference in text file format in handling carriage return (Enter)
- dos2unix [filename] will convert the input file to UNIX format, so the warning should go away.

## Using Standard Template Library (STL)

### Why STL?

- Included in the C++ Standard Library
- Allows to use key data structure and I/O interface easily
- Objects behaves like built-in data types

### Key classes

- Strings library : <string>
- Input/Output Handling : <iostream>, <fstream>, <sstream>
- Variable size array : <vector>
- Other containers : <set>, <map>, <stack>

## STL in practice

### sortedEcho.cpp

```
#include <iostream>
#include <string>
#include <vector>
#include <algorithm>
int main(int argc, char** argv) {
    std::vector<std::string> vArgs; // vector of strings
    for(int i=1; i < argc; ++i) {
        vArgs.push_back(argv[i]); // append each arguments to the vector
    }
    std::sort(vArgs.begin(),vArgs.end()); // sort the vector in alphanumeric order
    std::cout << "Sorted arguments :"; // print the sorted arguments
    for(int i=0; i < (int)vArgs.size(); ++i) { std::cout << " " << vArgs[i]; }
    std::cout << std::endl;
    return 0;
}
```

### A running example

```
user@host:~/> ./sortedEcho Hi hello world 123 1 2
Sorted arguments : 1 123 2 Hi hello world
```

## Using STL strings

```
int main(int argc, char** argv) {
    char* p = "Hello pointer"; // array of characters
    char* q = p; // q and p point to the same address
    p[0] = 'h';
    std::cout << p << std::endl; // "hello pointer"
    std::cout << q << std::endl; // "hello pointer"

    std::string s("Hello string"); // STL string
    std::string t = s; // clones the entire string
    t[0] = 'h';
    std::cout << t << std::endl; // "hello string"
    std::cout << s << std::endl; // "Hello string" : s isn't changed

    // Below are possible with std::string, but not with char*
    s += ", you are flexible"; // s becomes "Hello string, you are flexible"
    t = s.substr(6,6); // t becomes "string"
    return 0;
}
```

## Using STL vectors

```
int main(int argc, char** argv) {
    int A[] = {3,6,8}; // the array size is fixed
    int* p = A; // p and A points to the same array
    p[0] = 10;
    std::cout << ( A[0] == 3 ) << std::endl; // false, not any more

    std::vector<int> v; // vector is a variable-size array
    v.push_back(3); // v contains 3
    v.push_back(6); // v contains 3,6
    v.push_back(8); // v contains 3,6,8
    std::vector<int> u = v;
    u[0] = 10;
    std::cout << ( v[0] == 3 ) << std::endl; // true
    return 0;
}
```

## Algorithm INSERTIONSORT

**Data:** An unsorted list  $A[1 \cdots n]$

**Result:** The list  $A[1 \cdots n]$  is sorted

**for**  $j = 2$  **to**  $n$  **do**

```
    key = A[j];
    i = j - 1;
    while i > 0 and A[i] > key do
        A[i+1] = A[i];
        i = i - 1;
    end
    A[i+1] = key;
```

**end**

## insertionSort.cpp - User Interface

### insertionSort.cpp - main() function

```
int main(int argc, char** argv) {
    std::vector<int> v; // contains array of unsorted/sorted values
    int tok;           // temporary value to take integer input
    // read a series of input values from keyboard
    while ( std::cin >> tok ) { v.push_back(tok); }
    std::cout << "Before sorting:";
    printArray(v);    // print the unsorted values
    insertionSort(v); // perform insertion sort
    std::cout << "After sorting:";
    printArray(v);    // print the sorted values
    return 0;
}
```

### How to feed input values

- By keyword - type [input value]+[RET] per each input entry, and put Ctrl+D when finished

## STL Use in INSERTIONSORT Algorithm

### insertionSort.cpp - printArray() function

```
// print each element of array to the standard output
void printArray(std::vector<int>& A) {
    // call-by-reference to avoid copying large objects
    for(int i=0; i < (int)A.size(); ++i) {
        std::cout << " " << A[i];
    }
    std::cout << std::endl;
}
```

## STL Use in INSERTIONSORT Algorithm

### insertionSort.cpp - insertionSort() function

```
// perform insertion sort on A
void insertionSort(std::vector<int>& A) { // call-by-reference
    for(int j=1; j < A.size(); ++j) { // 0-based index
        int key = A[j]; // key element to relocate
        int i = j-1; // index to be relocated
        while( (i >= 0) && (A[i] > key) ) { // find position to relocate
            A[i+1] = A[i]; // shift elements
            --i; // update index to be relocated
        }
        A[i+1] = key; // relocate the key element
    }
}
```

## Recursion

### Short definition of recursion

Recursion See "Recursion".

### More complete definition of recursion

Recursion If you still don't get it, see: "Recursion"

### Key components of recursion

- A function that is part of its own definition
- Terminating condition (to avoid infinite recursion)

## Example of recursion

### Factorial

```
int factorial(int n) {
    if ( n == 0 )
        return 1;
    else
        return n * factorial(n-1); // tail recursion - can be transformed into loop
}
```

### towerOfHanoi

```
void towerOfHanoi(int n, int s, int i, int d) { // n disks, from s to d via i
    if ( n > 0 ) {
        towerOfHanoi(n-1,s,d,i); // recursively move n-1 disks from s to i
        // Move n-th disk from s to d
        std::cout << "Disk " << n << " : " << s << " -> " << d << std::endl;
        towerOfHanoi(n-1,i,s,d); // recursively move n-1 disks from i to d
    } // this is multi-way recursion, which cannot be easily written in loop
}
```

## Euclid's algorithm

### Algorithm GCD

**Data:** Two integers  $a$  and  $b$

**Result:** The greatest common divisor (GCD) between  $a$  and  $b$

**if  $a$  divides  $b$  then**

**return  $a$**

**else**

    Find the largest integer  $t$  such that  $at + r = b$ ;

**return  $GCD(r, a)$**

**end**

### Function gcd()

```
int gcd (int a, int b) {
    if ( a == 0 ) return b; // equivalent to returning a when b % a == 0
    else return gcd( b % a, a );
}
```

## A running example of Euclid's algorithm

### Function gcd()

```
int gcd (int a, int b) {
    if ( a == 0 ) return b; // equivalent to returning a when b % a == 0
    else return gcd( b % a, a );
}
```

### Evaluation of gcd(477, 246)

```
gcd(477, 246)
  gcd(231, 246)
    gcd(15, 231)
      gcd(6, 15)
        gcd(3, 6)
          gcd(0, 3)
gcd(477, 246) == 3
```

## Divide-and-conquer algorithms

Solve a problem recursively, applying three steps at each level of recursion

**Divide** the problem into a number of subproblems that are smaller instances of the same problem

**Conquer** the subproblems by solving them recursively. If the subproblem sizes are small enough, however, just solve the subproblems in a straightforward manner.

**Combine** the solutions to subproblems into the solution for the original problem

## Binary Search

```
// assuming a is sorted, return index of array containing the key,
// among a[start..end]. Return -1 if no key is found
int binarySearch(std::vector<int>& a, int key, int start, int end) {
    if ( start > end ) return -1; // search failed
    int mid = (start+end)/2;
    if ( key == a[mid] ) return mid; // terminate if match is found
    if ( key < a[mid] ) // divide the remaining problem into half
        return binarySearch(a, key, start, mid-1);
    else
        return binarySearch(a, key, mid+1, end);
}
```

## Recursive Maximum

```
// find maximum within an a[start..end]
int findMax(std::vector<int>& a, int start, int end) {
    if ( start == end ) return a[start]; // conquer small problem directly
    else {
        int mid = (start+end)/2;
        int leftMax = findMax(a,start,mid); // divide the problem into half
        int rightMax = findMax(a,mid+1,end);
        return ( leftMax > rightMax ? leftMax : rightMax ); // combine solutions
    }
}
```

## Using STL's sort : stdSort.cpp

```
#include <iostream>
#include <fstream>
#include <vector>
#include <algorithm>
int main(int argc, char** argv) { // sorting software using std::sort
    int tok;
    std::vector<int> v;
    if ( argc > 1 ) { // if argument is given, read from file
        std::ifstream fin(argv[1]);
        while( fin >> tok ) { v.push_back(tok); }
        fin.close();
    }
    else { // read from standard input if no argument is specified
        while( std::cin >> tok ) { v.push_back(tok); }
    }
    std::sort(v.begin(), v.end()); // Sort using the algorithm in STL
    for(int i=0; i < v.size(); ++i) {
        std::cout << v[i] << std::endl; // print out the content
    }
    return 0;
}
```

## Using insertionSort : insertionSort.cpp

```
#include <iostream>
#include <fstream>
#include <vector>
void insertionSort(std::vector<int>& v); // insertionSort as defined before
int main(int argc, char** argv) {
    int tok;
    std::vector<int> v;
    if ( argc > 1 ) {
        std::ifstream fin(argv[1]);
        while( fin >> tok ) { v.push_back(tok); }
        fin.close();
    }
    else {
        while( std::cin >> tok ) { v.push_back(tok); }
    }
    insertionSort(v); // differs from stdSort in only this part
    for(int i=0; i < v.size(); ++i) {
        std::cout << v[i] << std::endl;
    }
    return 0;
}
```

## STL Use in INSERTIONSORT Algorithm

### insertionSort.cpp - insertionSort() function

```
// perform insertion sort on A
void insertionSort(std::vector<int>& A) { // call-by-reference
    for(int j=1; j < A.size(); ++j) { // 0-based index
        int key = A[j]; // key element to relocate
        int i = j-1; // index to be relocated
        while( (i >= 0) && (A[i] > key) ) { // find position to relocate
            A[i+1] = A[i]; // shift elements
            --i; // update index to be relocated
        }
        A[i+1] = key; // relocate the key element
    }
}
```

## Running time comparison

### Running example with 200,000 elements

```
user@host:~$ time sh -c 'seq 1 200000 | ~hmkang/Public/bin/shuf | ./insertionSort > /dev/null'
0:17.42 elapsed, 17.428 u, 0.017 s, cpu 100.0% ...
user@host:~$ time sh -c 'seq 1 200000 | ~hmkang/Public/bin/shuf | ./stdSort > /dev/null'
0:00.36 elapsed, 0.346 u, 0.042 s, cpu 105.5% ...
```

### Why is the speed so different?

- If you didn't compile with -O option, the code is not optimized and it will be substantially slow (but the above example is compiled with -O)
- The time complexity of insertion sort is  $\Theta(n^2)$ , but the time complexity of STL's sorting algorithm is  $\Theta(n \log n)$ .

## Next Lecture

- Merge Sort
- Quicksort
- Lower bound of comparison-based sorting algorithms
- Elementary data structures